Tuning Your Decoder with Decoder Pro.



These days, sound decoders are so advanced that you can wear your pencil out recording all the settings you change, and in some cases there are so many things to enter that I do not even think about doing it without the computer.

I use a programme called **Decoder Pro** to programme and record all the decoders. It is easy to use, is regularly updated for new decoders and most of all it is free.

It means I do not have to remember or look up which CV to change or what each CV does. You just enter a number, or move a slider or just tick a box, the programme does the rest. Connecting the computer to your system can be very easy – **Decoder Pro** will connect to 38 different command systems.

The cable runs from your PC to your command station and that is all that should be needed. There are instructions on the web site for the initial set up of each system so I will not repeat them here. You can buy a unit that can be used for testing and programming your locos if you do not have your own system. Many of you may take your locos to a club or mate's place to run them but would like set up your own locos at home – a more favourable environment. This unit is called a <u>Sprog</u> and is available from the UK for about \$100.00. (There is also a Dealer in Glen Innes, NSW.) I use a Sprog 3 for all my programming N scale through to O scale.

http://jmri.org/download/

REMEMBER – set the loco up the way YOU want it, not for Claude at the club.

Start up Decoder and Programmer selection

You'll get a new window to configure the programmer with information about a specific type of decoder, or an existing locomotive. This will become your locomotive roster as you program your decoders.

M DecoderPro: All Entries

File Edit Settings Actions SPROG Programmer EasyDCC via Serial Window Help

Roster Groups All Entries	ID	DCC Address	Icon	Decoder Model
Don Tydd	CEFX1006	1006		AT100LC/KT100LC Diesel
Gerry Hopkins	GN 1012	1012		TSU-1000 DRGW K-Class Steam
Peter Jackson	BNSF 1016 bh	1016		WOW Diesel 101 SS2
Warren	NSW 1018 mw	1018		M1
	GN 1028	1028		TSU-1000 Lt Logging Steam
	GN 1056 gh t4	1056		T4X
	GN 1056 gh v4	1056		WOW Steam 101 SS4
	LMS 1072 gm	1072		ECO-200 UK Steam
	NSW 1100	1100		D13SR

To start working with a newly-installed decoder, click the adjacent "**New Loco**" button to open the list of decoders, then have the programmer read the decoder and attempt to identify it. (You could also explicitly tell the programmer the decoder type). While the programmer is talking to the decoder, status will be displayed in the bottom of the window; "Idle" or "OK" means that things are working. If it succeeds, it will select the decoder model in the selection box. Usually it will only be able to narrow the selection down to a

few choices. Check that the right model is selected in the "Decoder Installed" box, update the selection if desired.

The first screen lets you set up the ID for the file containing all the changes you make to the decoder. It also has the space to set up other data and notes for you own personal use.

Nothing technical here just straight forward information you can type in.

S Ba	Sound Function sic Speed Control	Volume Group	s Individua Speed Ta	l Volume 0 ble	Individ
	ID: Road Name: Road Number: Manufacturer:	ANR 24 dg			
	Owner: Model:				
	DCC Address:	24 DCC St	iort 😪		
	Throttle Speed Limit: Comment:	100 % 🗘		^	
		<		>	
	Decoder Family: Decoder Model:	WOW Diesel Sou WOW Diesel 101			
	Decoder Comment:			^	
		<		>	
	Date Modified:	10/05/2018 2:15	5:42 PM		
		Save to Roster	Reset to defaults	3	

The next screen is called **BASIC** and as the name implies, it has the basic detail information for identifying the loco such as the number on the side of the cab, direction, number of speed steps and whether it can run on DC as well.

Short (one t	oyte) address
O Long (two b	yte) address
Active Address:	
24	
Drimon : Address	24
Primary Address	
Extended Address	0
Address Format	Short (one byte) address
N	e contra contra
Normal direction of motion	
Speed steps	28/128 ~
	Off ~

This image shows the **number** on the cab and as it is only two digits it is referred to as Short Address.

Also shown here is the **direction** of travel, depending on the decoder you may have to change the way the lights operate but that is on another pane.

Speed Steps this is normally set to 28/128 the old option on decoders was 14 speed steps but many modern decoders do not have this option.

Analog Conversion Mode means the loco can run on DC as well as DCC. It is always advised to turn off the DC option for numerous technical reasons if you are only using DCC.

Click "Write Changes". Once this pane is set up we can go on and set our preferred options for the loco.

Accel 1 Rate	1
Decel 1 Rate	1
Dither Frequency	3
Dither Amplitude	10
BEMF Enable	Enabled ~
BEMF Cut Out	0
Motor Button Control	Disabled
Button Control Direction	Manual F2 for, F3 rev \vee
Power to button controlled motor	255
Enable BEMF Button Control	Displad

The next pane is the **Motor Control** pane. Here you can set up the Acceleration and Deceleration rates. My advice for a starting point is to set Accel to 25 and Decel to 15.

This will work well for most decoders – ESU decoders would have these set - Accel to 100 and Decel to 60 for the same effect.

The rest of the setting on this pane can be left at default for now. The information here will vary depending on the Brand and whether it is non-sound or sound.



The next basic step is to set the top speed of your loco. This is a must if you intend to run locos together – it is called "speed matching" but more of that later.

As most decoders have **B**ack **E**lectro **M**otive **F**orce the start voltage can be left at "0" for now.

We must set the **Maximum Voltage** then the **Midpoint Voltage**. We do this by sliding pointer along the scale until the desired speed is obtained then set the Min Point to about half this.

An out of the box typical British 4-4-0 loco can run at 230mph – just a little too fast. As a rule of thumb, top speed would be set at 30mph for most locos. **Remember** – with DCC you walk with your train to observe signals, sound the bell, sound whistle/horn as required so 30mph is a good speed. This is a good speed when you walk around a layout that has other operators in aisles.

"With DCC you drive the train NOT the layout."

The next pane in **Decoder Pro** is the **SPEED TABLE**. There are 28 speed steps and without Decoder Pro you can program all the steps individually with your command station.

Thanks to Decoder Pro you can do it all in a few easy steps. You can click on the first step and set its value then click on the last step (setting your top speed) and click match ends. The table sets itself up as shown here. Remember to click the circle at the top.



White Wire Effect 0	Constant bright light 🛛 🗸
White Wire Effect Group	Group 0 🗸
White Wire Timing	Function on running forward
Yellow Wire Effect 0	Constant bright light v
Yellow Wire Effect Group	Group 0 🗸
Yellow Wire Timing	Function on running reverse
Green Wire Effect 0	Constant bright light V
Green Wire Effect Group	Group 0 \vee
Green Wire Timing	Function on both directions
Purple Wire Effect 0	Constant bright light \sim
Purple Wire Effect Group	Group 0 \vee
Purple Wire Timing	Function on both directions
Brown Wire Effect 0	Constant bright light \sim
Brown Wire Effect Group	Group 0 \vee
Brown Wire Timing	Function on both directions
Pink Wire Effect 0	Constant bright light \sim
Pink Wire Effect Group	Group 0 🗸
Dipk Wire Timing	Function on both directions

The next "FUN" pane is the **Light Output** pane. Here you can see the 6 outputs on this decoder. The **EFFECT** can be set to one of many different effects – these do vary with many decoders. Just click on the down arrow at the end of the line and you will see all the effects available in that decoder.

You can also set the output to operate in either direction or in both directions. With a number of decoders there is a further option to control the brightness of each output – it saves having to "play" with different resistors in line with the light.



Lighting Outputs . . . What function does what.

Use this s	sheet to	o deterr	nine wh	iich fund	ctions w	ill con	trol w	hich o	utputs		
Description	Output wire or operation										
	1	2	3	4	5	6	Dim	Ditch	Motor	BEMF	Brake
		Yellow	Green	Purple	Brown	Pink			-		_
Forward Headlight F0(f)											
Reverse Headlight FO(r)		\sim									
Function 1											
Function 2											
Function 3											
Function 4						\square					
Function 5											
Function 6											
Function 7											
Function 8											
Function 9											
Function 10											
Function 11											
Function 12											

On this pane we can select which function controls which output or outputs. A Function button can control a number of outputs such as **Rotary Beacon** as well as a **cab light** or **step lights**, each one on a different output.

You can also see here that there are other options available on this decoder. These often include Dim, Ditch Lights, Brakes and possibly turn the BEMF on or off.

You can have a lot of fun playing with this page.

Decoder Pro with Sound Decoders

To start working with a newly-installed sound decoder, click the adjacent "**New Loco**" button to open the list of decoders, then have the programmer read the decoder and attempt to identify it.

The first part is exactly the same as with non-sound decoders. With the newer decoders Decoder Pro reads a few extra CVs to get the correct sound file and firmware version. The **Tsunami 2** has a limited memory for the sound files so they are split into groups – Steam, Alco, GE, EMD, Baldwin and other. The WOW has a bit more memory – currently 8GB Micro SD Card – so all steam sounds are on one decoder and all diesels are on another decoder. The Loksound decoder has 32k of memory so only a single sound file is loaded.

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	LMS 1072 gm	1072		ECO-200 UK Steam
	NSW 1100	1100		D13SR

(You could also explicitly tell the programmer the decoder type). While the programmer is talking to the decoder, status will be displayed in the bottom of the window. If it succeeds, it will select the decoder model in the selection box. Usually it will only be able to narrow the selection down to a few choices. Check that the right model is selected in the "Decoder Installed" box; update the selection if desired.

The Basic screen is the same as the one used for non-sound decoders. The next screen is the Motor Control screen and this often has a little more on it just in case you have a loco that is a little "lazy" to start. The Basic Speed Control is the same as before and is adjusted in the same way.

The **Function Pane** is something different and varies across brands.

In the **Tsunami 2** any function between "0 and "28" can be assigned to any of the sounds or outputs. Alongside any sound or light output there is a drop down box – just click here and assign a Function Button to it.

		Exten Func Mapp	tion	Forward Driving	Reverse Driving	Forward Standing	Reverse Standing	Emergency Stop Button
	Headlight	FO	~					
Ba	ckup Light	FO	~					
	FX3 Effect	F1	~					
	FX4 Effect	F1	~					
	FX5 Effect	F9	~					
	FX6 Effect	F9	~					
	Dimmer	F11	\sim					
	Mute	F8	\sim					
Independent/	Train Brake	F7	~					
	Half Speed	F14	~					
Momentu	m Override	F14	\sim					
Grade Crossing Signal	Disable		\sim					
Forward Whistle Signal	Disable		~					
Reverse Whistle Signal	Disable		~					
Stop Whistle Signal	Disable		~					
E	rake Select	F12	~					
Alternate Mixer	Disable	A11	~					
	RPM+	F5	~					
	RPM-	11	~					
	Airhorn	F2	~					
Bell	Disable	12	~					

Read changes on sheet Write changes on sheet Read full sheet Write full sheet

The **Loksound** is different again and much of the sound allocation depends on the sound file that has been loaded. The Function mapping can be changed but this is best done with the Loksound Programmer.

t	ł	Conditions (Motion, Direction, F keys, Sensors)		Physical Outputs (Wires)		Logical Functions		Sounds		
	Row	(notani) an eccani) i nojaj a anaraj		(Row
0	1	Stopped,Forward	Change	-	Change	-	Change	۲ <u>ــــــــــــــــــــــــــــــــــــ</u>	Change	1
0	2	Stopped,Reverse	Change	÷	Change	÷	Change	•	Change	2
0	3	Moving,Forward	Change	÷	Change	-	Change	•	Change	3
0	4	Moving, Reverse	Change		Change	•	Change	•	Change	4
0	5	Forward,F0,not F19	Change	Headlight[1]	Change	-	Change	nd slot 11, Sound slot 13, Sound slot 14	Change	5
0	6	ie 3,not F26,not F27,not Wheel Sensor	Change	Aux 7,Aux 8,Aux 1[2]	Change	•	Change	Sound slot 20	Change	6
0	7	F1	Change	•	Change	÷	Change	Sound slot 1, Sound slot 2	Change	7
0	8	F2	Change	÷.	Change		Change	Sound slot 3	Change	8
0	9	F3	Change	*	Change	-	Change	Sound slot 4	Change	9
0	10	F4	Change		Change	-	Change	Sound slot 5	Change	10
0	11	F5	Change		Change		Change	Sound slot 6	Change	11
0	12	F6	Change		Change	Momentum off Shunting Mode	Change		Change	12

In the **TCS WOW** there are 28 Function Buttons and you can assign any one of 380 sounds to any button. This is opposite to the Tsunami 2.



When mapping sounds – use the functions you want and put them where you want.

All the three brands mentioned above have a further option to calibrate the **B**ack **E**lectro **M**otive Force. To get the best performance from your decoder follow the instructions in the maker's manual as they are completely different to set up.

VOLUME is an individual choice – BUT – if you can hear the loco from more than 8 feet away – it is too loud.

So far I have only covered the basic Tuning of the Decoder – choice of sounds and their settings are an interesting session and would relate to your individual choice and your age. Next is a simple as possible explanation of BEMF just for your information.

BEMF and Sound.

I will try to keep this as simple and basic as possible, it does apply to the mainstream sound decoders such as Tsunami 1, Tsunami 2, Econami and WOWs. Soundtraxx gave it the name of Dynamic Digital Exhaust and this seems to cover them all.

Each motor has "dead" spots when under power, at these spots the motor acts as a generator and generates a pulse – **B**ack **E**lectro **M**otive Force. These pulses are seen by the processor and are used to control the motor speed.

When the throttle is set to a particular speed – the motor will turn at that speed – expected - BUT if the decoder has momentum set correctly then there is a difference between the speed set and the actual speed – the processor reads the **BEMF** to see this and increases the sound (the chuffs for a steam loco) until the motor gets to the set speed and then quietens down.

If the loco comes to a grade the motor will try to slow down but the processor sees the change in speed (by reading the BEMF) and adjust the power to the motor accordingly – hence the chuff gets loader. In both the Tsunami 2 and the WOW v4 this is part of the High BEMF calibration.

When the loco is going downhill, provided the rolling stock is free rolling, the motor will try to speed up. The processor sees this and reduces the power to the motor – this is controlled by the Low BEMF calibration. At the bottom of the grade the loco will have to work again until the motor is turning at the set speed – then the chuff will drop back.

Very slight changes in grade or curve radius will affect the BEMF and cause changes to the sound. To get the best response the momentum should be set realistically. I personally use 25 for acceleration and 120 for deceleration - using the brake for stopping.

Besides the Low & High settings there are other adjustments – rate at which the sound changes, how often it reads the BEMF, how big is the window through which it reads.

The above is as simple as I can explain it. There are many advanced algorithms in the decoder to give you the best results – we do not need to know the nitty gritty here just how to use it.

Model Railroading is Fun.

Gerry Hopkins MMR

Further reading

http://nmra.org.au/Hints/Decoder%20Pro%20Clinic%202018.pdf

http://nmra.org.au/Hints/Decoder%20Hints/Decoders%20hints%20and%20tips.pdf

http://nmra.org.au/Hints/Program%20Track/Program%20Track.html

http://nmra.org.au/Hints/Turnout Tips/Turnout Tips.html